

Optimal Transport Modeling of Cellular Differentiation: From Low-Rank Structure to Temporal Dynamics

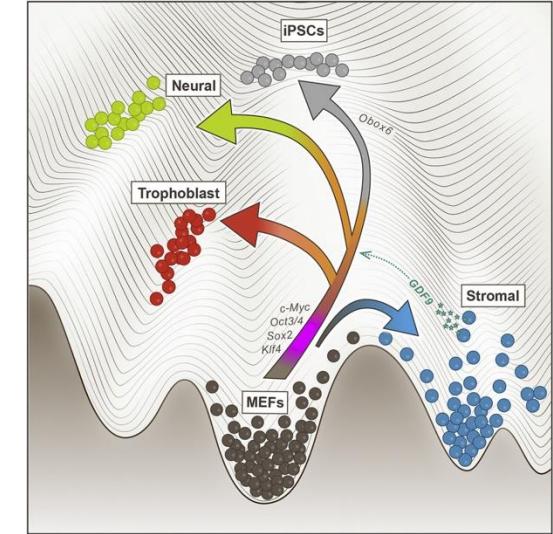
Speaker: Peter Halmos

Joint work with Julian Gold, Xinhao Liu, and Ben Raphael

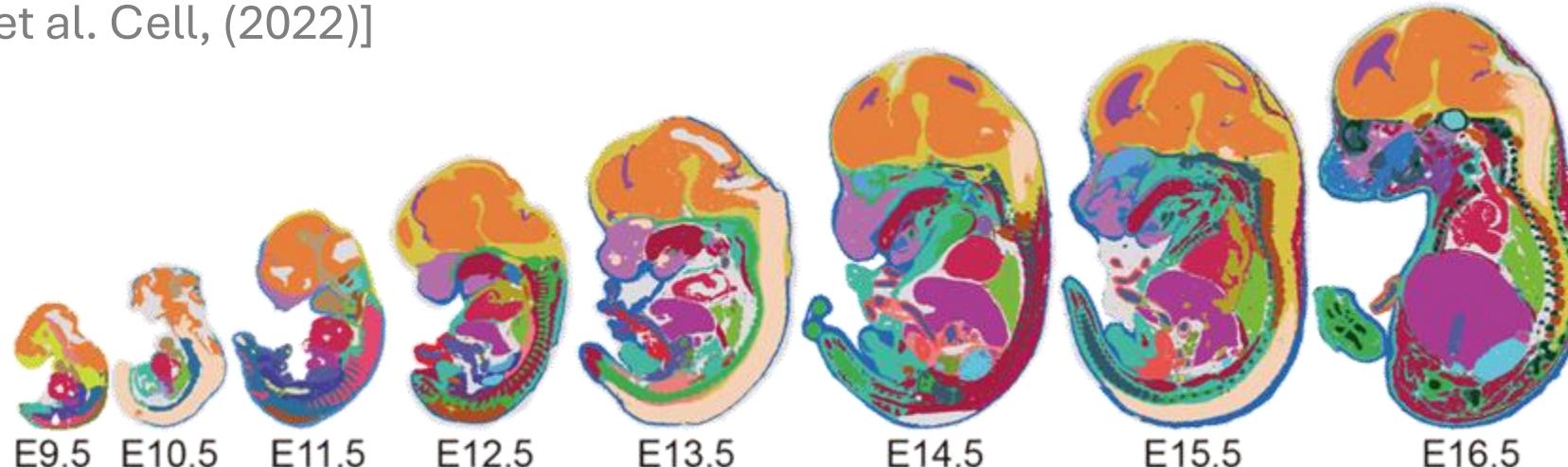


Temporal and Spatiotemporal transcriptomics: Sequencing across multiple time points during developmental and reprogramming processes

Reprogramming of fibroblasts to induced pluripotent stem cells [Schiebinger, et al. Cell, (2019)]



Spatial Transcriptomics of mouse embryos across 8 developmental stages
[Chen, et al. Cell, (2022)]

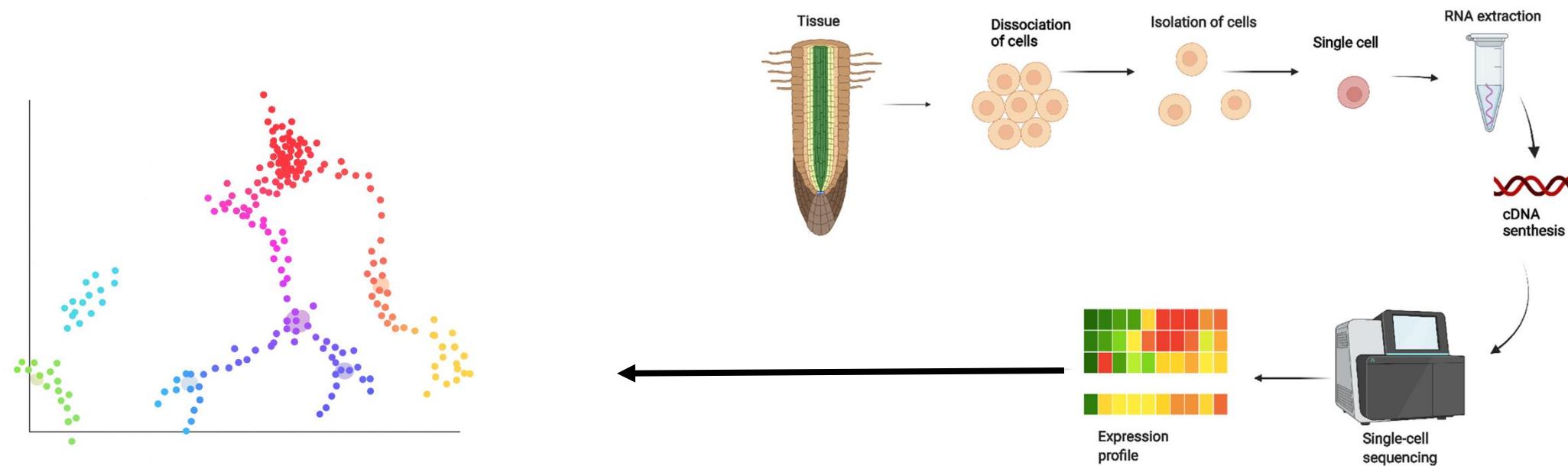


*And others!
(Pijuan-Sala et al.,
Nature, 2019)
(Liu et
al. Developmental
Cell, 2022)

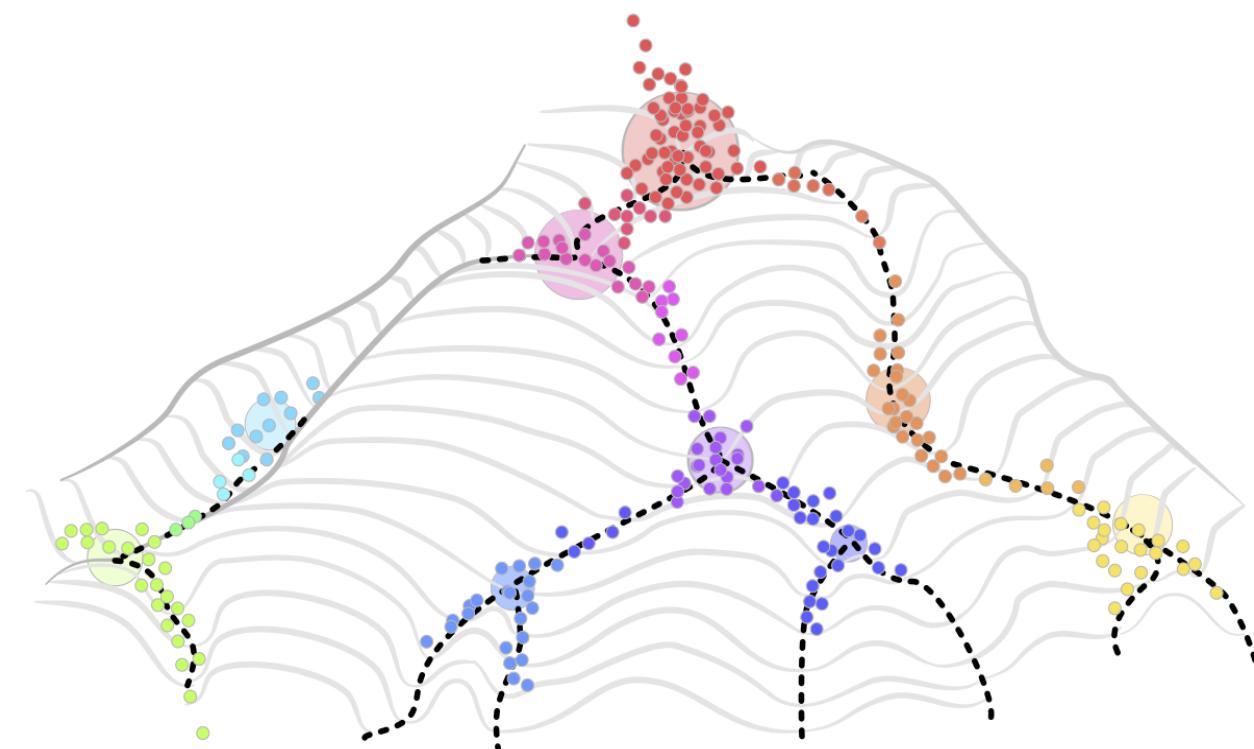
...

Defining Cell State Space

- Two key experimental technologies: **Single-cell transcriptomics** and **Spatial transcriptomics**.
 - **Transcriptomics**: D-dimensional “state-space” of vector with scalar expression of the mRNA for each protein in cell ($= \mathbb{R}^D$)
 - **Single cell**: Cell i is its transcriptional state $X^{(i)} \in \mathbb{R}^D$
 - **Spatial transcriptomics**: Cell i is its transcriptional state $X^{(i)} \in \mathbb{R}^D$ augmented with a spatial position $s^{(i)} \in \mathbb{R}^2$ or 3



Temporal and Spatiotemporal transcriptomics: Opens the Analysis of Fundamental Biological Questions!



The "Waddington Landscape"

Questions:

1. Ancestor-descendant relationships between cells across two timepoints?
2. Cell-states or types which index the temporal process of development?
3. Trajectories between these cell types?

Limitations:

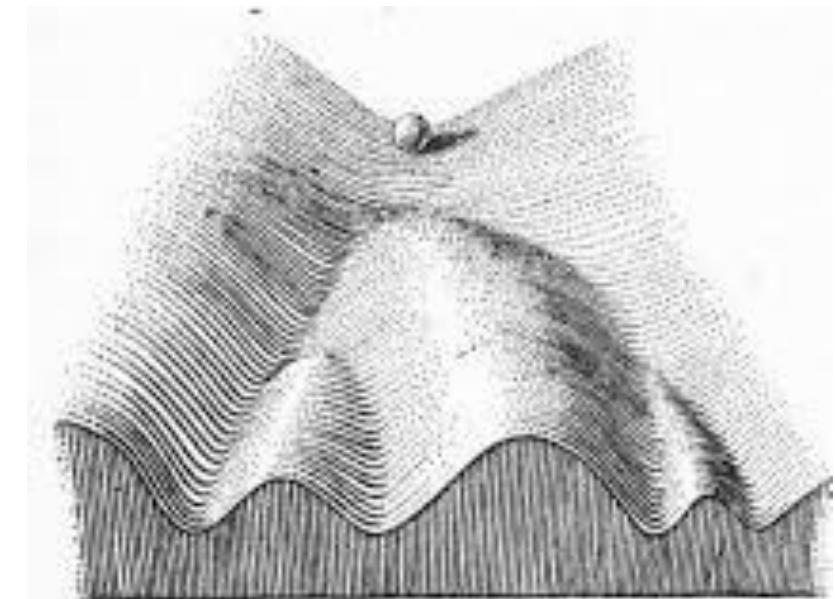
- Technology is destructive – each sample from a different individual
- Do not have ground-truth trajectories!

Waddington Potential Landscape

- What's a reasonable modeling assumption for how cells evolve?
- In *The Strategy of the Genes* '57, C.H. Waddington Conjectured:
 - Cell differentiation pathways \approx A gradient-flow on a potential landscape

i.e. minimize $V(x)$ via dissipative descent:

$$\dot{x} = -\nabla V(x)$$



The "Waddington Landscape"
Photo cred: (Waddington, 1957)

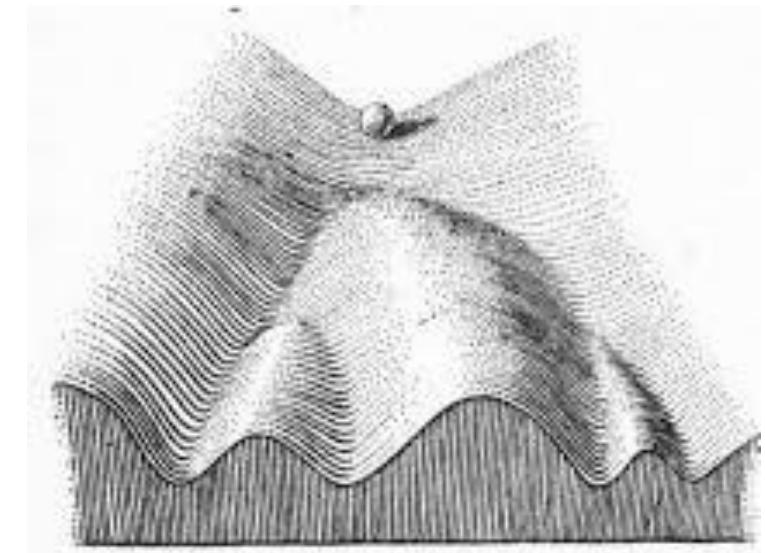
Waddington Potential+ Landscape

- Since we observe cell distribution marginals at different time-points $\rho_t(x)$ with stochasticity, one needs to augment the particle-flow view!
- This can be viewed as a descent over the particle-distribution $\rho_t(x)$ itself with Langevin dynamics ([Biondo '25](#), [Lavenant & Schiebinger '21](#))

Continuity-equation: probability mass
(rather than points) flows down landscape

$$\partial_t \rho_t = \nabla \cdot (\rho_t \nabla V) + T \Delta \rho_t$$

$$dX_t = -\nabla V(x)dt + \sqrt{2T}dB_t$$



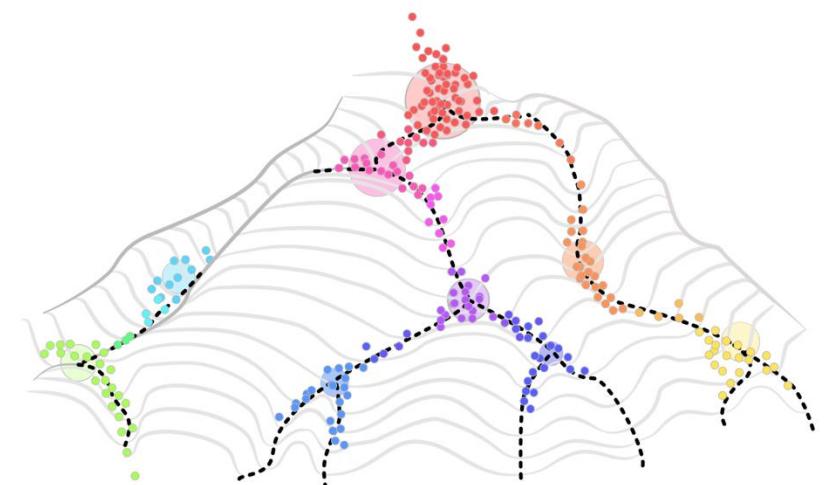
Resolving Trajectories on the Landscape

- There are a few practical difficulties with applying this model:
 1. We do not know the landscape a priori
 2. We only observe discrete “snapshots”

$$\left(\rho_t = \frac{1}{n_t} \sum_{i=1}^{n_t} \delta_{x_i} \right)_{t=1}^N$$

generated from the unknown landscape.

- 3. Without the landscape, we do not know which cells transitioned to which!

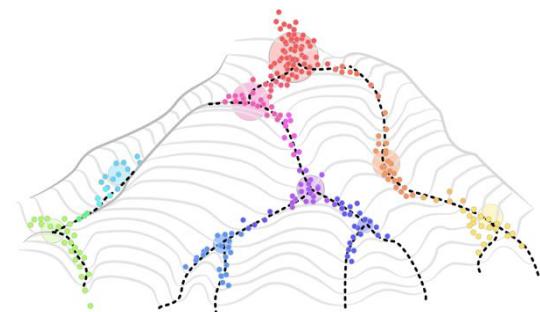


Resolving Trajectories on the Landscape

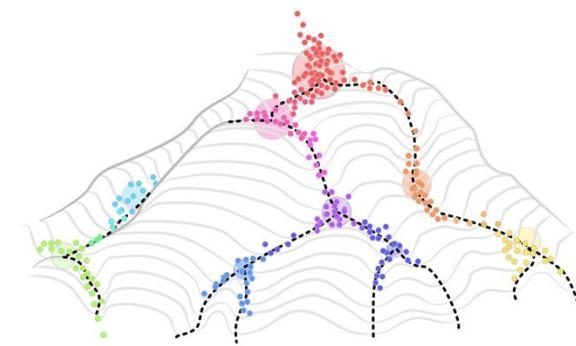
- Let's look at a pair of densities ρ_0, ρ_1 and apply Occam's Razor to the velocities which can take $\rho_0 \rightarrow \rho_1$:

Q: What is the time-varying distribution ρ_t and velocity field v_t of **least kinetic energy** between the two distributions?

$$\inf_{(\rho_t, v_t)} \left\{ \int_0^1 \int_{\mathbb{R}^d} \|v_t\|_2^2 \rho_t(dx) \mid \partial_t \rho_t = -\nabla \cdot (\rho_t v_t), \rho_0 = \rho_{t=0}, \rho_1 = \rho_{t=1} \right\}$$



Solution: Optimal Transport!



- **(Benamou & Brenier, 2000):** The minimal kinetic energy value for this probability-flow is the Wasserstein distance of optimal transport (OT)

$$\inf_{(\rho_t, v_t)} \left\{ \int_0^1 \int_{\mathbb{R}^d} \|v_t\|_2^2 \rho_t(dx) \mid \partial_t \rho_t = -\nabla \cdot (\rho_t v_t), \rho_0 = \rho_{t=0}, \rho_1 = \rho_{t=1} \right\} \\ = W_2^2(\rho_0, \rho_1) !$$

- The optimal velocity field is given by the transport map! We can **just** solve for OT velocity directly. Coincides with gradient flow velocity in limit of taking the time-interval to zero (**Jordan, Kinderlehrer & Otto, '98**): discrete OT on fine time-intervals can recover any dynamics.

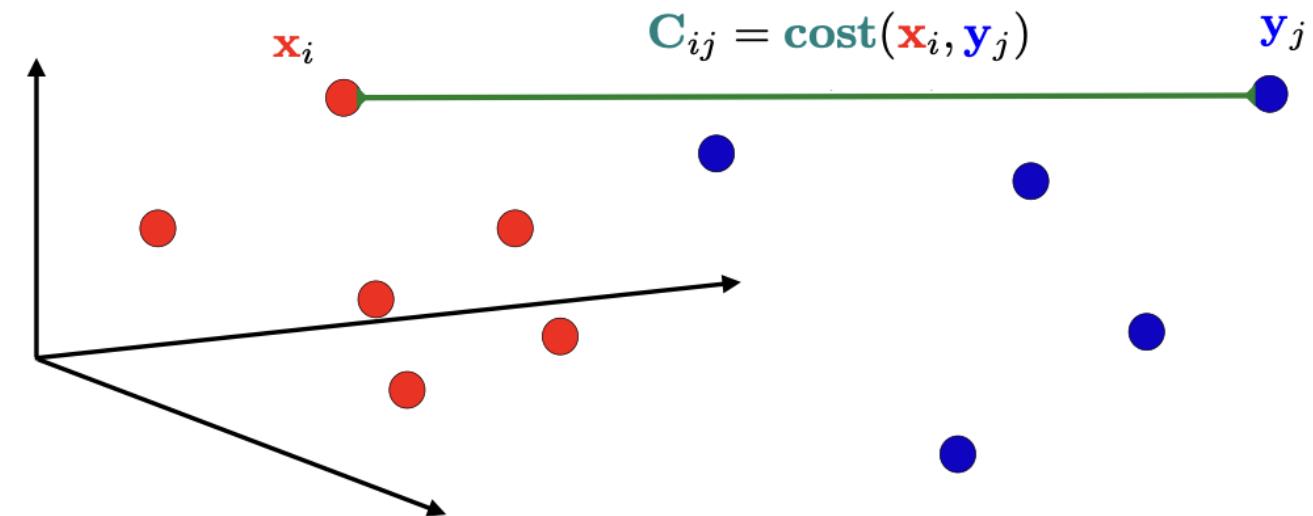
Conclusion: OT is “*most natural*” choice!

Discrete Optimal Transport

- Practically, when $\rho_0 = \sum_{i=1}^{n_0} \mathbf{a}_i \delta_{x_i}$ and $\rho_1 = \sum_{j=1}^{n_1} \mathbf{b}_j \delta_{y_j}$, (usually uniform), OT is solved by the discrete optimization problem:

$$\mathbf{P}^* = \underset{\mathbf{P} \in \Pi(\mathbf{a}, \mathbf{b})}{\operatorname{argmin}} \langle \mathbf{C}, \mathbf{P} \rangle$$

$$= \underset{\mathbf{P} \in \Pi(\mathbf{a}, \mathbf{b})}{\operatorname{argmin}} \sum_{i,j} \mathbf{C}_{ij} \mathbf{P}_{ij}$$

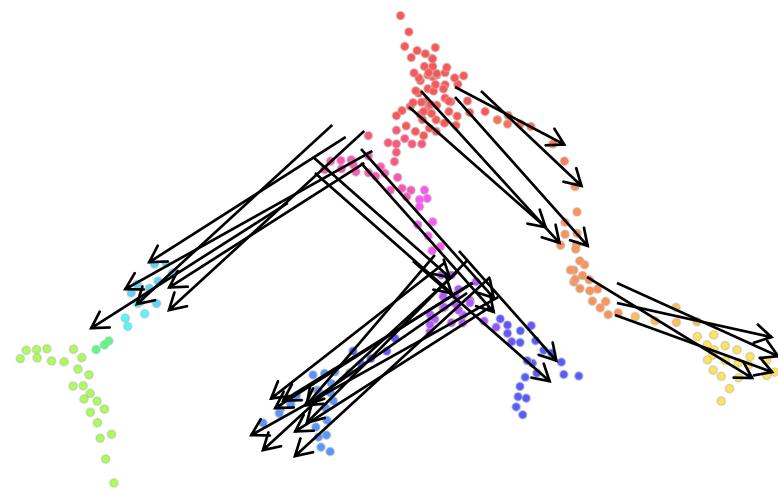


$$\Pi(\mathbf{a}, \mathbf{b}) = \{ \mathbf{P} \in \mathbb{R}_+^{n \times m} : \mathbf{P} \mathbf{1}_m = \mathbf{a}, \mathbf{P}^T \mathbf{1}_n = \mathbf{b} \}$$

Existing Techniques for Optimal Transport

- Many existing methods map the time-dynamics of cells using variations of optimal transport (Schiebinger et al 2019, Zeira et al 2022, Klein et al 2025, Liu & Halmos et al 2025) with great success
- However, they infer full-rank structure through cell-cell couplings, as opposed to *low-rank* structures in the mapping

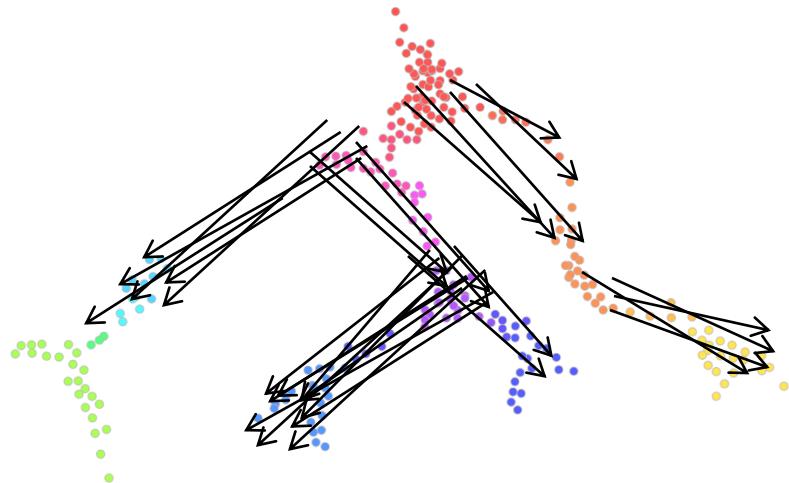
Cell-to-cell Coupling: Full-rank structure



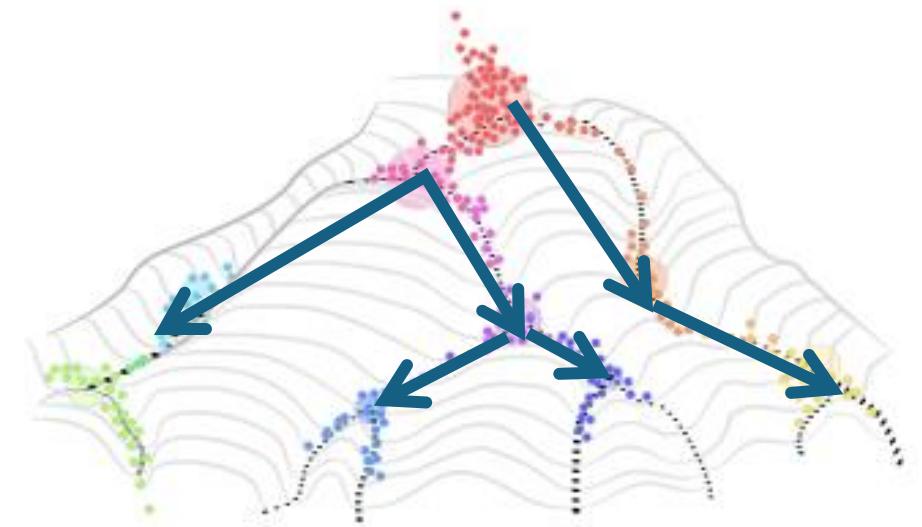
Low-Rank Structure in the Transport

- OT maps (without entropy regularization) are bijections
- No true low-rank structure and *flat* spectrum of singular values = 1!

Cell-to-cell Coupling: Full-rank structure

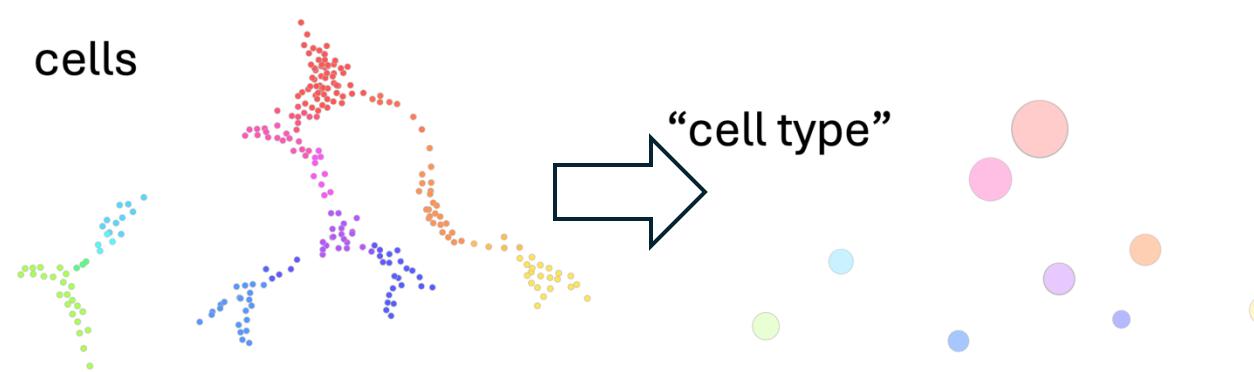


Latent Trajectories: *Low-Rank* Structure

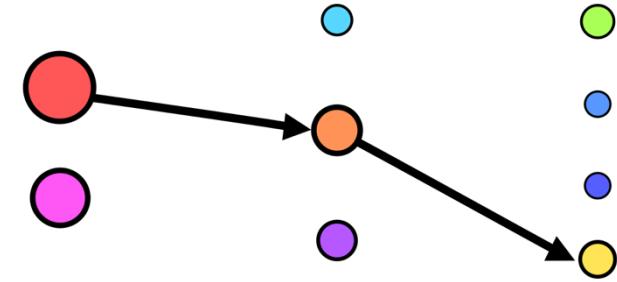


Low-Rank Structure in the Transport

- Examples of low-rank structure in the transport include latent cell-state and the *differentiation map* between these states
 - The “canals” or “latent-trajectories” of Waddington’s landscape are **low-rank** structures!
- Existing techniques assume cell-state inference is *distinct* from transport and don’t bridge the two.



A *cell-type* is a coarse-graining of cells into clusters.

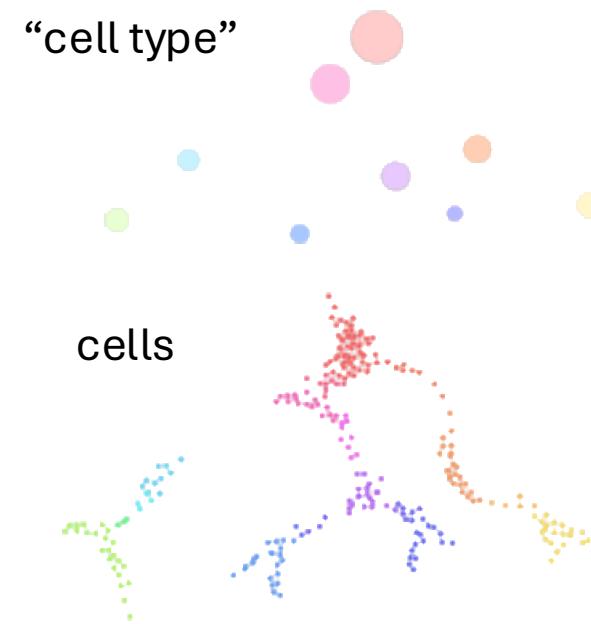
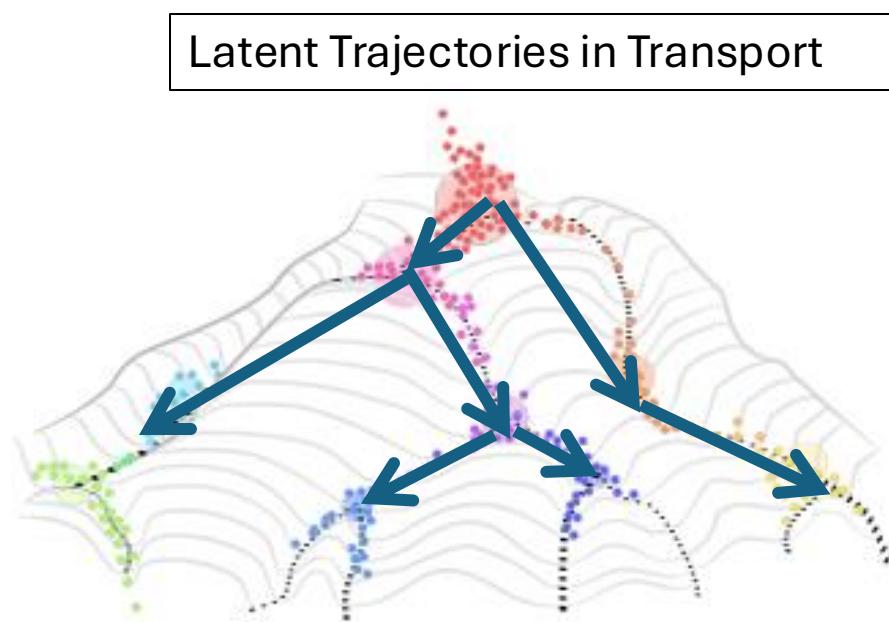


A *differentiation map* is a directed acyclic graph giving the ancestral relationship between cell-types.

Latent Trajectories over Cell-State

Our work addresses the following questions:

1. What cell-states "index" the temporal development process?
2. What is the *differentiation map* (DAG) between these cell states?

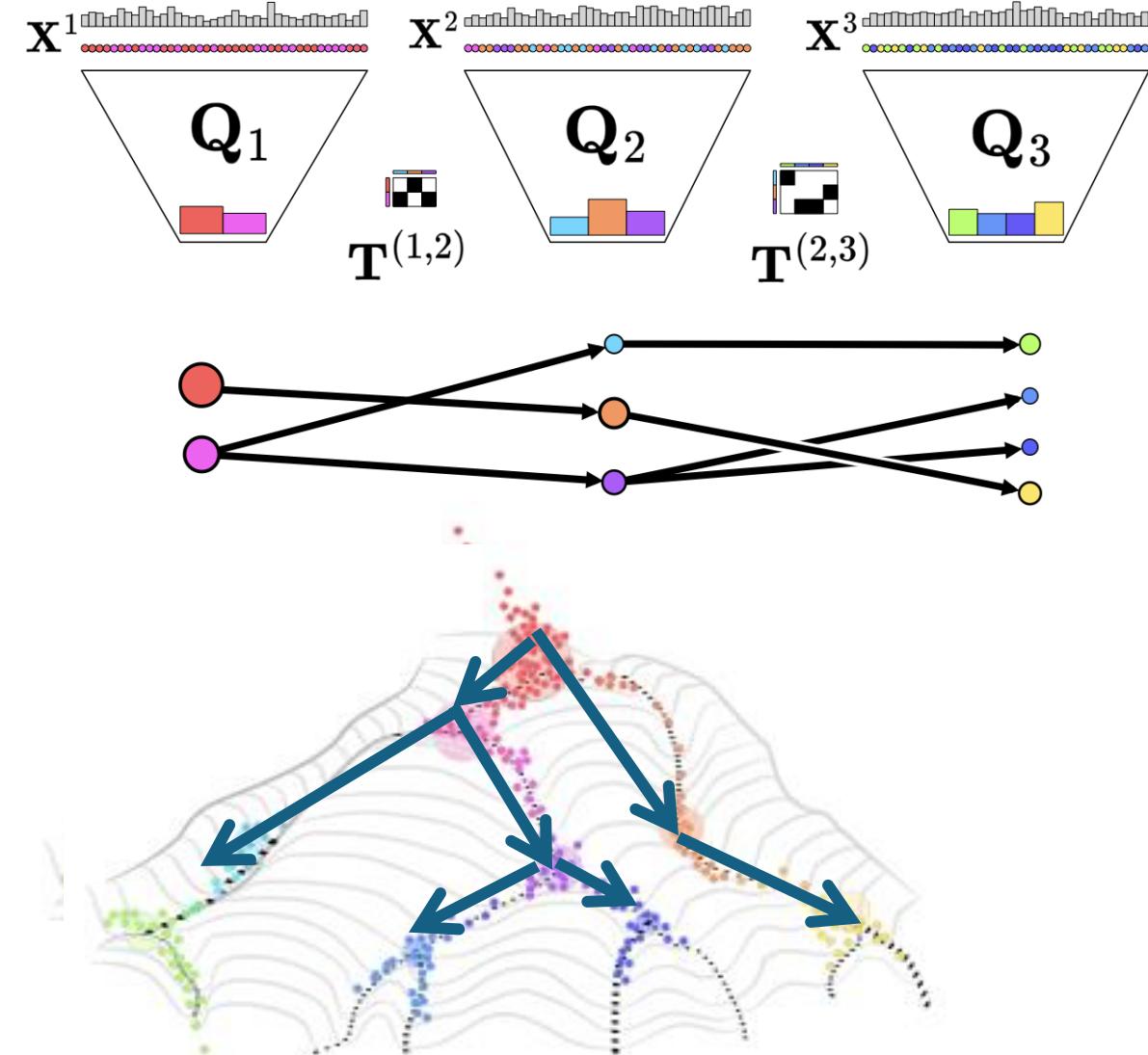


Hidden Markov Optimal Transport (HM-OT)

(1) Discovers latent cell types and aligns individual cells to them.

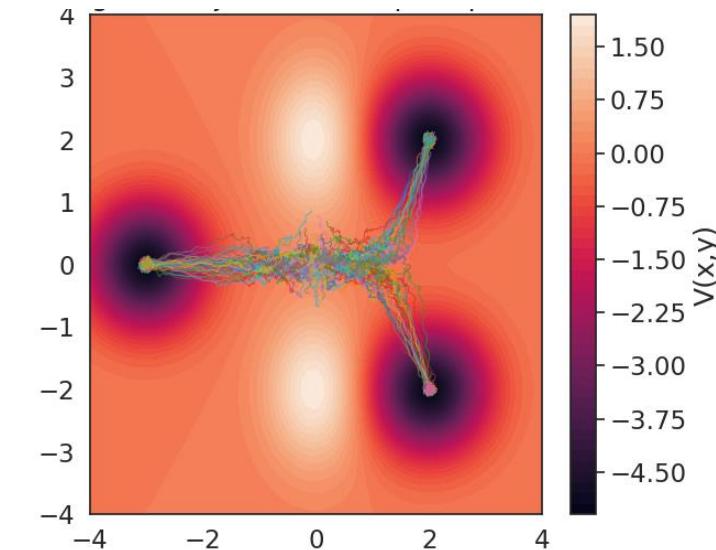
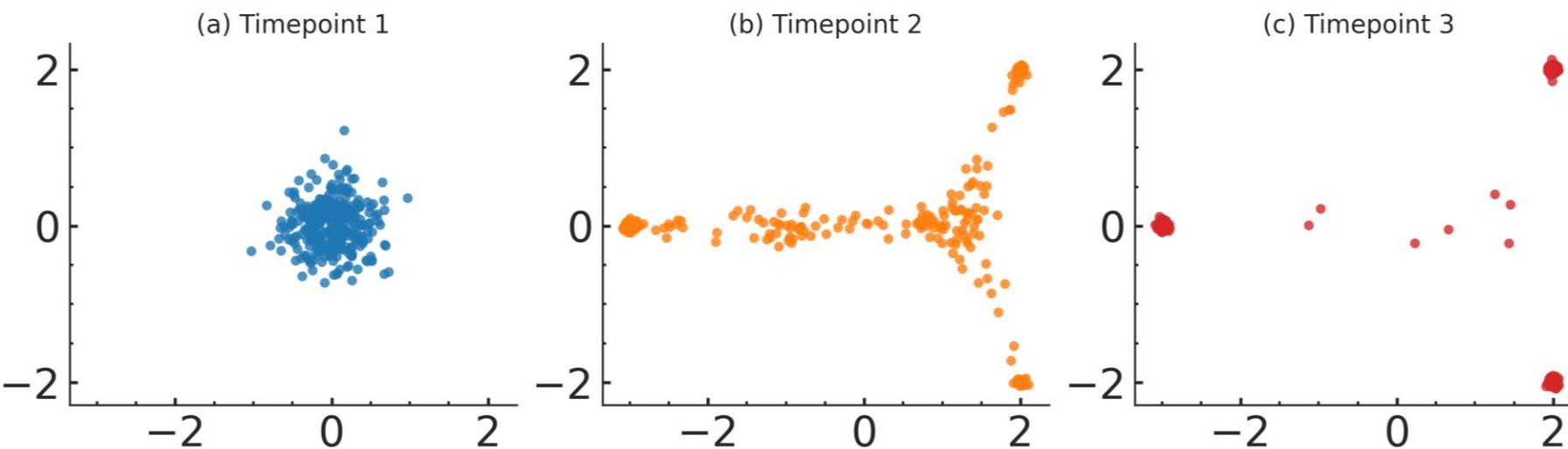
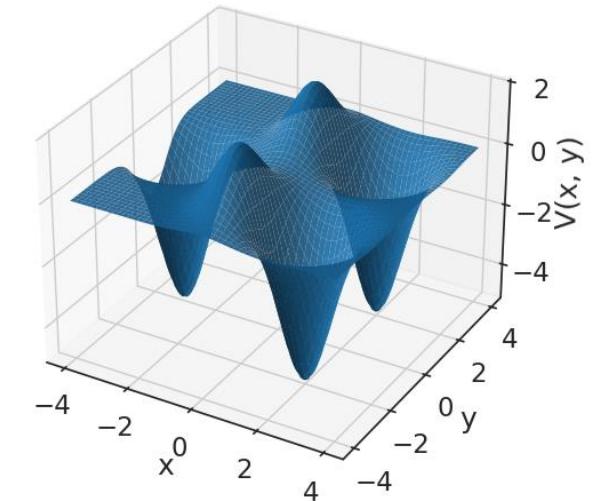
(2) Maps between the cell types while minimizing an optimal transport cost.

(3) Uses *low-rank optimal transport* (Forrow et al '19, Scetbon et al '20, Lin et al '21, Halmos et al '24) to do (1) and (2) simultaneously across multiple timepoints.



Example: Langevin on Tristable Potential

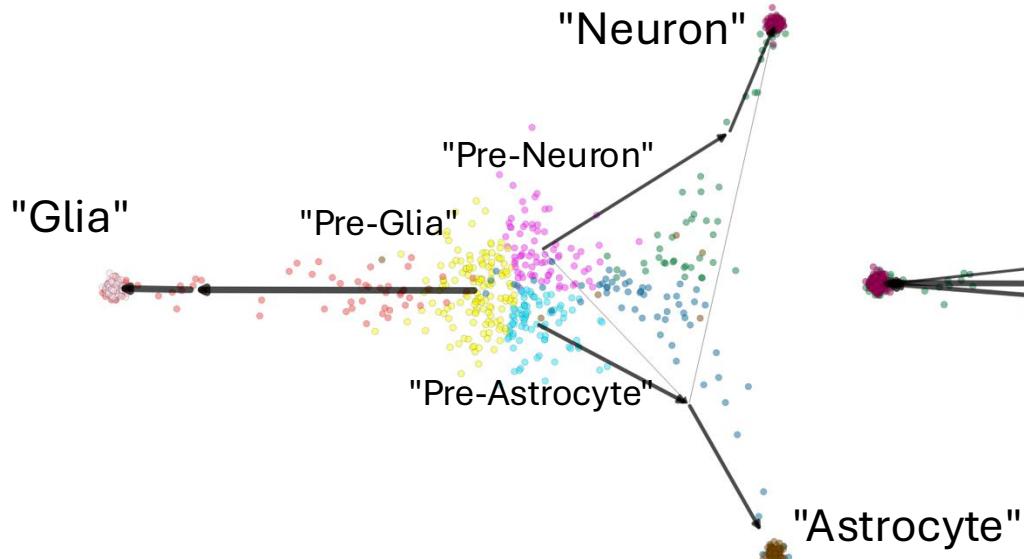
- Existing techniques assume cell-state inference is *distinct* from transport. *Where does this go wrong?*
- Suppose cells follow Langevin on a tristable landscape (**Bhattacharya '11**) and we measure trajectories at 3 timepoints



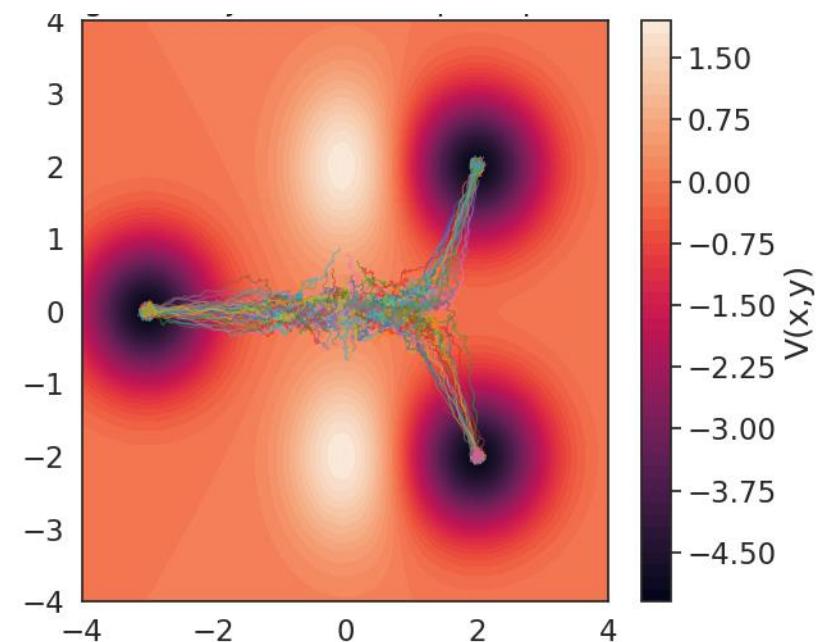
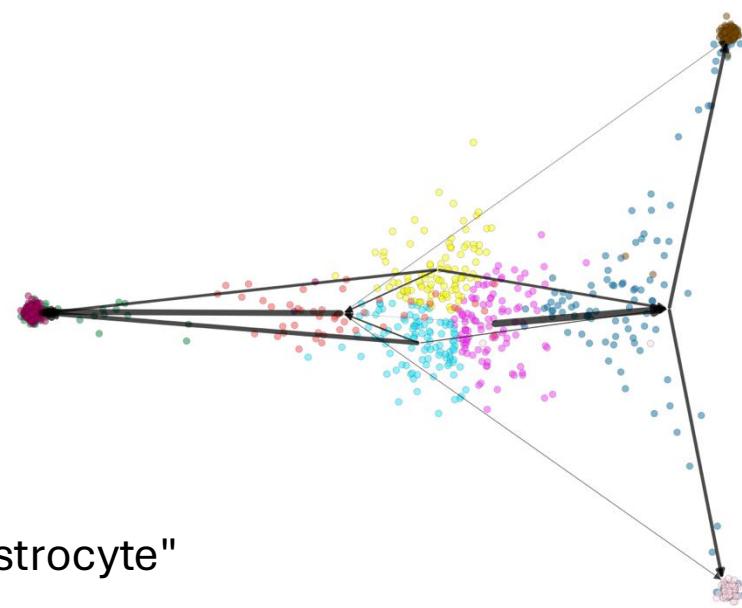
Example: Langevin on Tristable Potential

- Clustering at each timepoint independently + full-rank OT fails to identify the three true latent trajectories on the tri-stable landscape.
- Latent trajectories must be optimized *jointly* with the transport!

Hidden-Markov OT (HM-OT)



Clustering + Full-rank OT



Low-rank OT: Latent Structure in Transport

- A rank- r coupling P may always be represented (Scetbon '21, Cohen & Rothblum) by the factorization

$$P = Q \text{diag}(g^{-1}) R^\top$$

- *Low-rank* optimal transport (Farrow '19, Scetbon '21) solves primal OT with this factorization

(Parametrization)

$$P = Q \text{diag}(1/g) R^\top$$

(Loss)

$$\mathcal{L}_{\text{LOT}} := \langle C, Q \text{diag}(1/g) R^\top \rangle$$

(Constraints) $\text{FC}_{a,b}(r) := \{(Q, R, g) \in \mathbb{R}_+^{n \times r} \times \mathbb{R}_+^{m \times r} \times (\mathbb{R}_+^*)^r : Q \in \Pi_{a,g}, R \in \Pi_{b,g}\}$

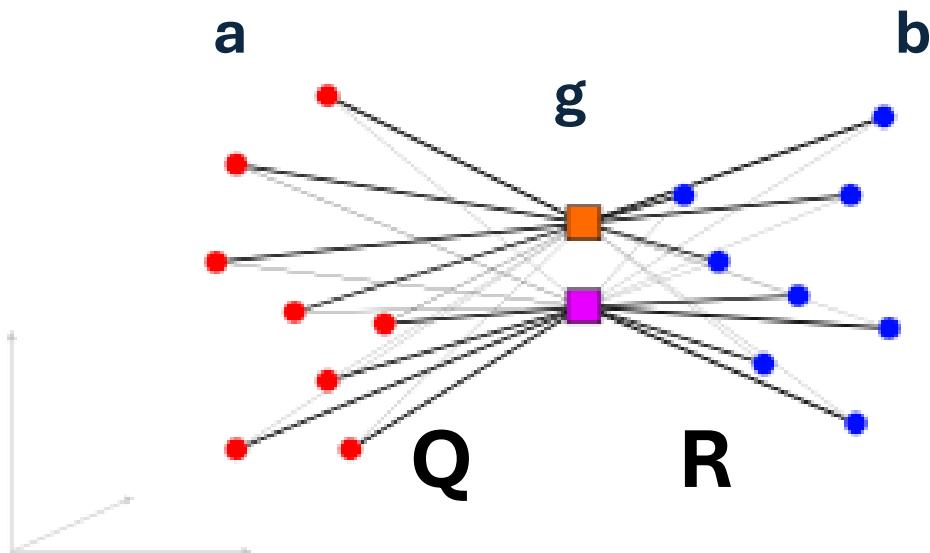
Low-rank OT: Latent Structure in Transport

$$\mathbf{P} = \mathbf{Q} \text{diag}(\mathbf{g}^{-1}) \mathbf{R}^\top$$

“Outer marginal:” the points

$$\mathbf{Q} \mathbf{1}_r = \mathbf{a}, \mathbf{R} \mathbf{1}_r = \mathbf{b}$$

Low-rank OT

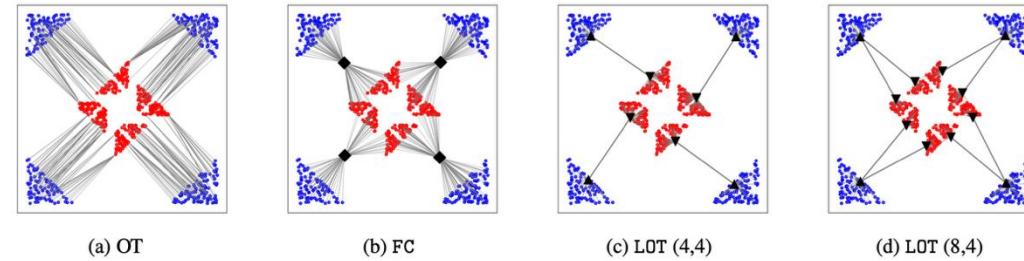


“Inner marginal:” the latent co-clusters

$$\mathbf{g} = \mathbf{Q}^\top \mathbf{1}_n = \mathbf{R}^\top \mathbf{1}_n$$

Low-rank OT: key benefits

1. It captures **latent, interpretable** structure in the transport (Forrow '19, Lin '21) with *linear* complexity.
2. It offers a framework for ***co-clustering*** and generalizes K-means to a pair of datasets (Scetbon '22).
3. Full-rank OT ***can reduce to*** low-rank OT with linear space and **$O(n \log n)$ time*** with Hierarchical Refinement (Halmos&Gold, ICML '25).

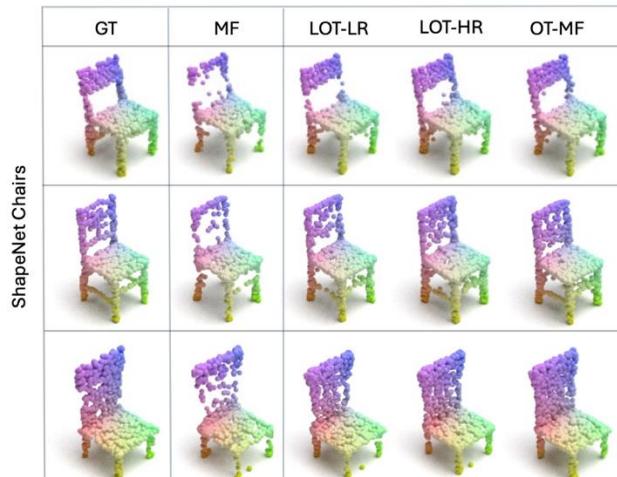
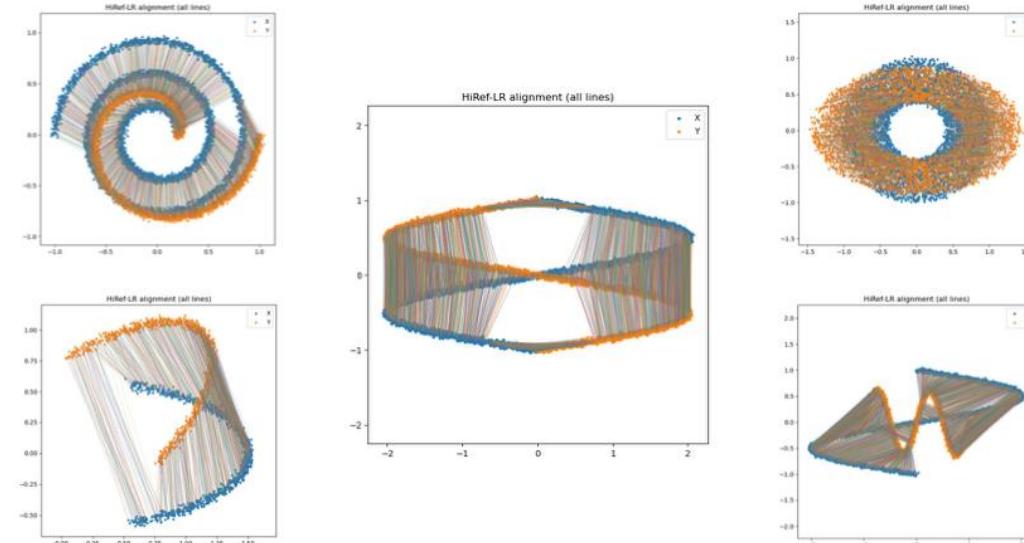


(a) OT

(b) FC

(c) LOT (4,4)

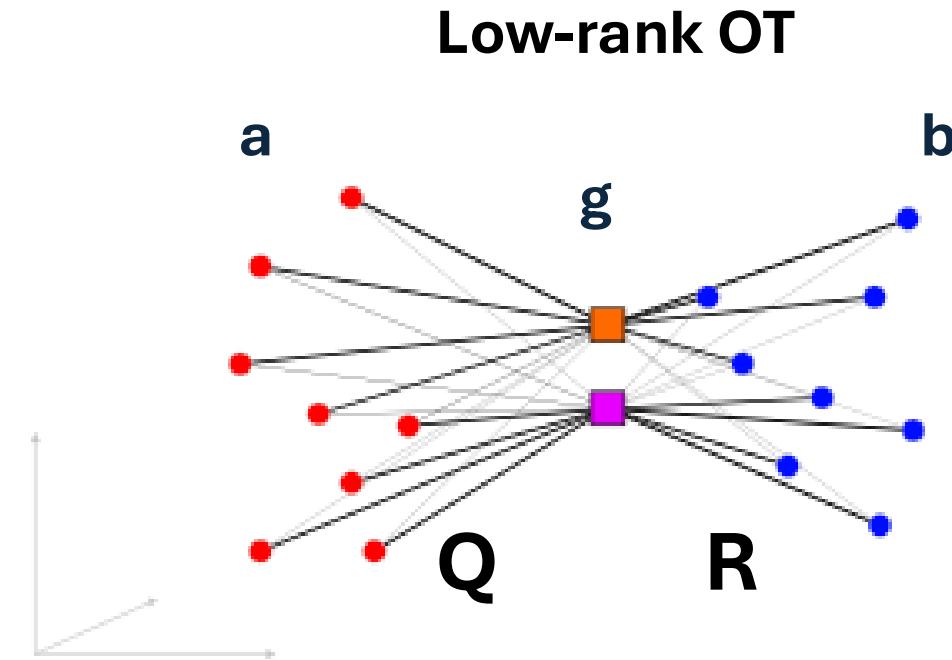
(d) LOT (8,4)



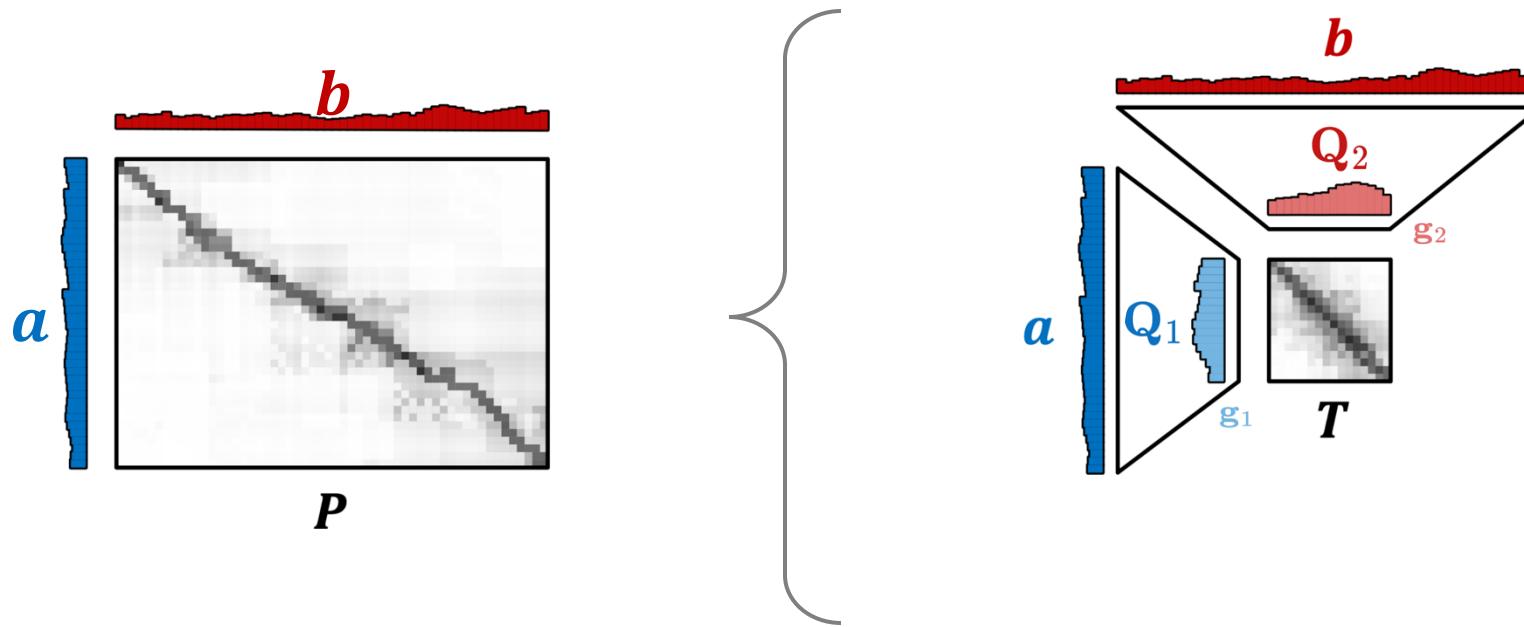
Low-rank Optimal Transport

- One issue with this factorization: It does not account for hidden transition or DAG structure!

$$\mathbf{P} = \mathbf{Q} \text{diag}(\mathbf{g}^{-1}) \mathbf{R}^\top$$



Low-Rank Optimal Transport with Latent Coupling: A Special Parametrization

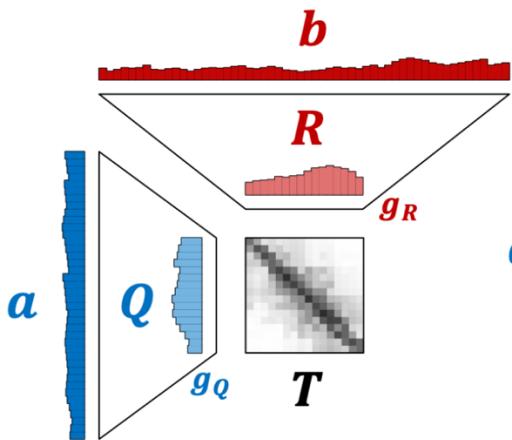


Factor relaxation with latent coupling (FRLC)

Low rank approximation of optimal transport

Halmos*, Liu*, Gold*, R. NeurIPS (2024)

Factor-Relaxation and Latent Coupling



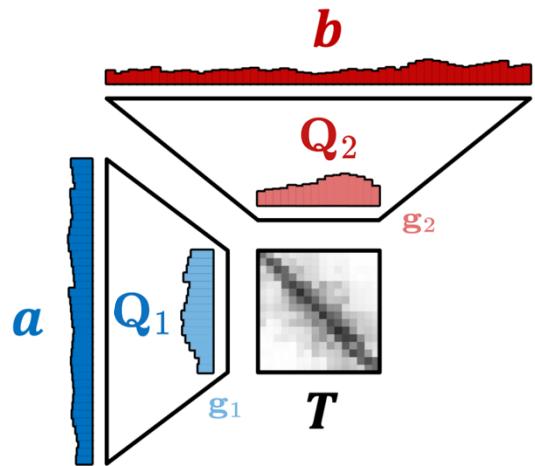
- LC (latent coupling) parametrization decouples problem using coordinate mirror-descent, with the introduction of a *latent coupling* \mathbf{T} between two inner marginals \mathbf{g}_Q and \mathbf{g}_R

(Parametrization) $\mathbf{Q} \text{diag}(1/\mathbf{g}_Q) \mathbf{T} \text{diag}(1/\mathbf{g}_R) \mathbf{R}^T =: \mathbf{P}_{(Q, R, T)}$

(Loss) $\mathcal{L}_{\text{LC}}(\mathbf{Q}, \mathbf{R}, \mathbf{T}) := \langle \mathbf{C}, \mathbf{P}_{(Q, R, T)} \rangle_F,$

(Constraints) $\text{LC}_{\mathbf{a}, \mathbf{b}}(r) := \{(\mathbf{Q}, \mathbf{R}, \mathbf{T}) \in \mathbb{R}_+^{n \times r} \times \mathbb{R}_+^{m \times r} \times \mathbb{R}_+^{r \times r} : \mathbf{Q} \in \Pi_{\mathbf{a}, \cdot}, \mathbf{R} \in \Pi_{\mathbf{b}, \cdot}, \mathbf{T} \in \Pi_{\mathbf{g}_Q, \mathbf{g}_R}\}$

Factor-Relaxation and Latent Coupling (Algorithm)



Factor relaxation with latent coupling (FRLC)

Low rank approximation of optimal transport

Halmos*, Liu*, Gold*, R. NeurIPS (2024)

$$\begin{aligned} \mathbf{Q}_k &\leftarrow \tilde{\Pi}_{\mathbf{a}, \mathbf{g}_Q} (\mathbf{Q}_k \odot \exp(-\gamma_k \nabla_{\mathbf{Q}})) \\ \mathbf{R}_k &\leftarrow \tilde{\Pi}_{\mathbf{b}, \mathbf{g}_R} (\mathbf{R}_k \odot \exp(-\gamma_k \nabla_{\mathbf{R}})) \\ \mathbf{g}_Q, \mathbf{g}_R &= \mathbf{Q}_k^T \mathbf{1}_n, \mathbf{R}_k^T \mathbf{1}_m \\ \mathbf{T}_k &\leftarrow \Pi_{\mathbf{g}_R, \mathbf{g}_Q} (\mathbf{T}_k \odot \exp(-\gamma_T \nabla_{\mathbf{T}})) \end{aligned}$$

Efficiently solved with Mirror-Descent:
alternating Sinkhorn projections!

Interpretation of Latent Coupling

LC (latent coupling) factorization of P imposes *rank constraint* and decomposes P into 3 factors while keeping it a feasible coupling

$$\implies P = Q_1 \text{diag}(1/g_1) T \text{diag}(1/g_2) Q_2^T$$

$$Q_1 \in \Pi(a, g_1)$$

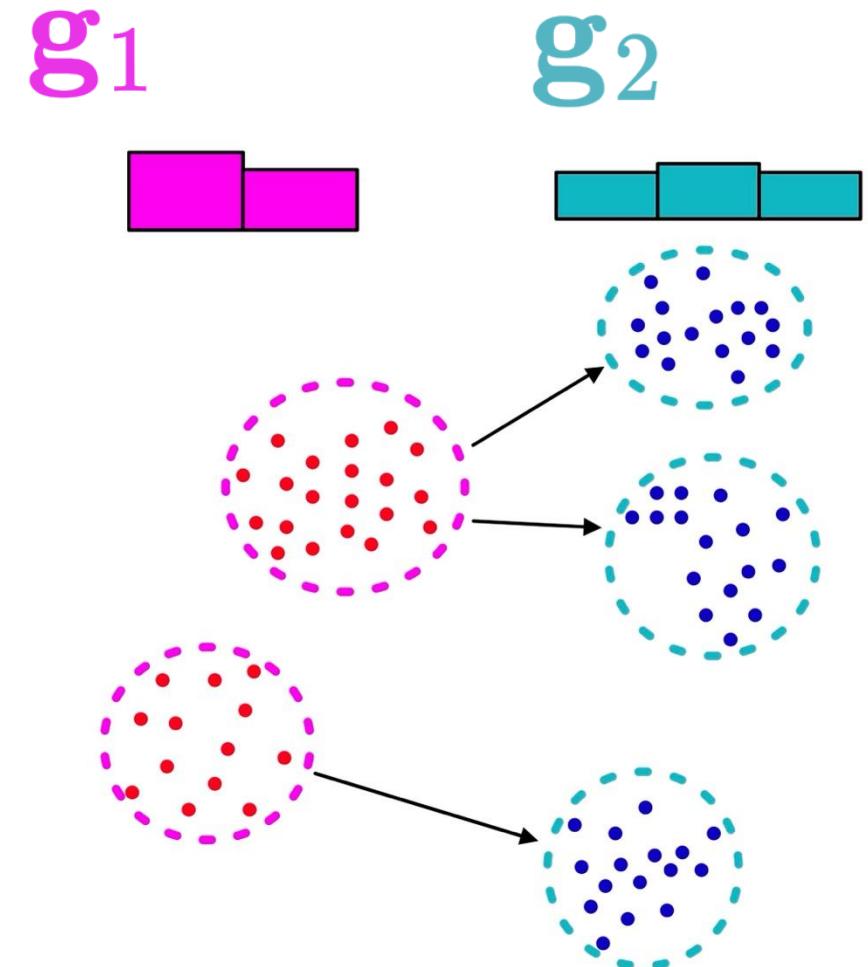
Couples point distribution at time 1 to cell-state distribution at time 1

$$T \in \Pi(g_1, g_2)$$

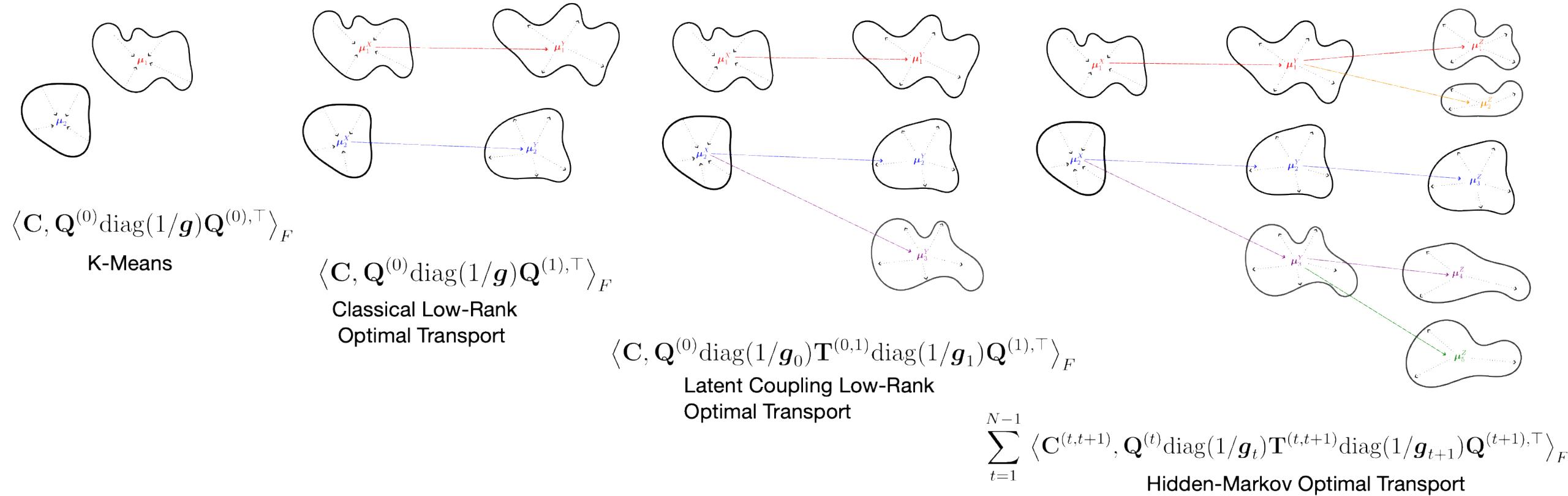
Couples cell-type distribution at time 1 to cell-state distribution at time 2

$$Q_2^T \in \Pi(g_2, b)$$

Couples cell-state distribution at time 2 to point distribution at time 2



Hidden-Markov OT: Linking Latent Trajectories *Through Time*



Hidden-Markov Optimal Transport

- The key idea of HM-OT is to (1) use the latent-coupling parametrization to capture cell differentiation and transitions, and (2) extend the loss function of low-rank OT to account for many timepoints
- Introduce cells encoded as distributions \mathbf{a}_t , cell-type vectors \mathbf{g}_t , and a coupling (latent representation) between these cells and their types \mathbf{Q}_t

Parametrization and constraints are same as FRLC, but with time index!

(Parametrization)	$\mathbf{P}^{(t,t+1)} := \mathbf{Q}_t \text{diag}(1/\mathbf{g}_t) \mathbf{T}^{(t,t+1)} \text{diag}(1/\mathbf{g}_{t+1}) \mathbf{Q}_{t+1}^T$
(Constraints)	$\mathbf{LC}_{\mathbf{a}_t, \mathbf{a}_{t+1}}(r_t, r_{t+1})$

Hidden-Markov Optimal Transport

- The factors need to be *linked* across time for cell-state to be defined consistently: multi-marginal extension of low-rank OT
- Cost minimizes the global distance of latent trajectories across time

Different loss! Generalized and linked across many timepoints.

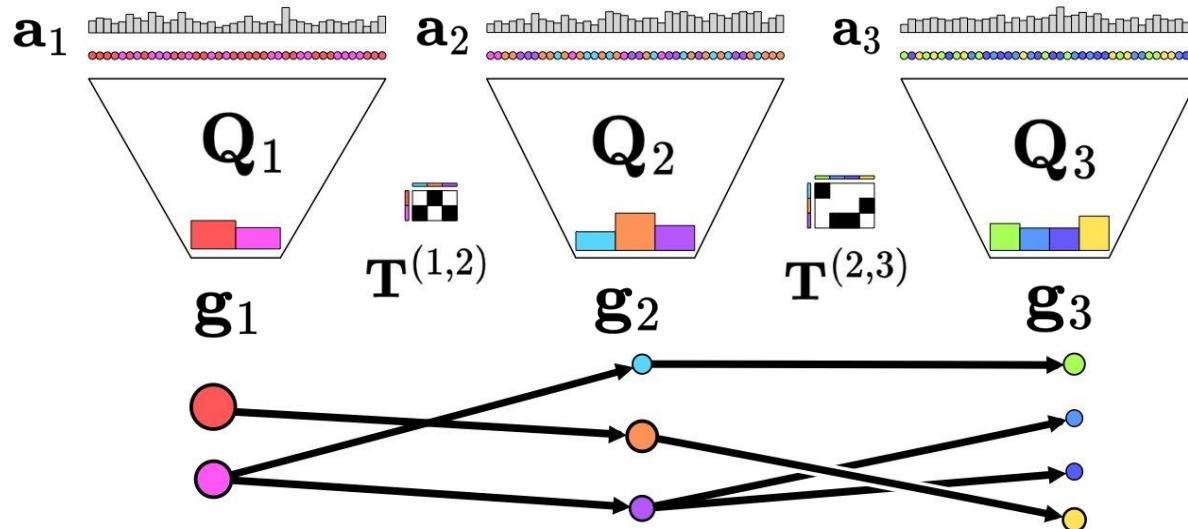
$$\text{(Loss)} \quad \min_{\mathbf{Q}, \mathbf{T} : (\mathbf{Q}_t, \mathbf{Q}_{t+1}, \mathbf{T}^{(t,t+1)}) \in \mathbf{LC}_{\mathbf{a}_t, \mathbf{a}_{t+1}}(r_t, r_{t+1})} \sum_{t=1}^{N-1} \langle \mathbf{C}^{(t,t+1)}, \mathbf{P}^{(t,t+1)} \rangle_F$$

Hidden-Markov Optimal Transport

Problem: Given empirical distributions $(\mathbf{a}_t)_{t=1,\dots,N}$ find the latent factors $(\mathbf{Q}_t)_{t=1,\dots,N}$ and differentiation maps $(\mathbf{T}^{(t,t+1)})_{t=1,\dots,N-1}$ that minimize the Wasserstein cost of the latent states through time.

$$\min_{\mathbf{Q}, \mathbf{T} : (\mathbf{Q}_t, \mathbf{Q}_{t+1}, \mathbf{T}^{(t,t+1)}) \in \text{LC}_{\mathbf{a}_t, \mathbf{a}_{t+1}}(r_t, r_{t+1})} \sum_{t=1}^{N-1} \langle \mathbf{C}^{(t,t+1)}, \mathbf{P}^{(t,t+1)} \rangle_F$$

$$\mathbf{P}^{(t,t+1)} := \mathbf{Q}_t \text{diag}(1/\mathbf{g}_t) \mathbf{T}^{(t,t+1)} \text{diag}(1/\mathbf{g}_{t+1}) \mathbf{Q}_{t+1}^T$$



Hidden-Markov OT (Algorithm)

- Decouples sequential problem in time into greedy Forward-Backward estimates of $(Q_t, T^{(t,t+1)}, g_t)$ which are solved with FRLC.
- Decoupling is like the forward-backward algorithm for Hidden Markov Models (HMM)

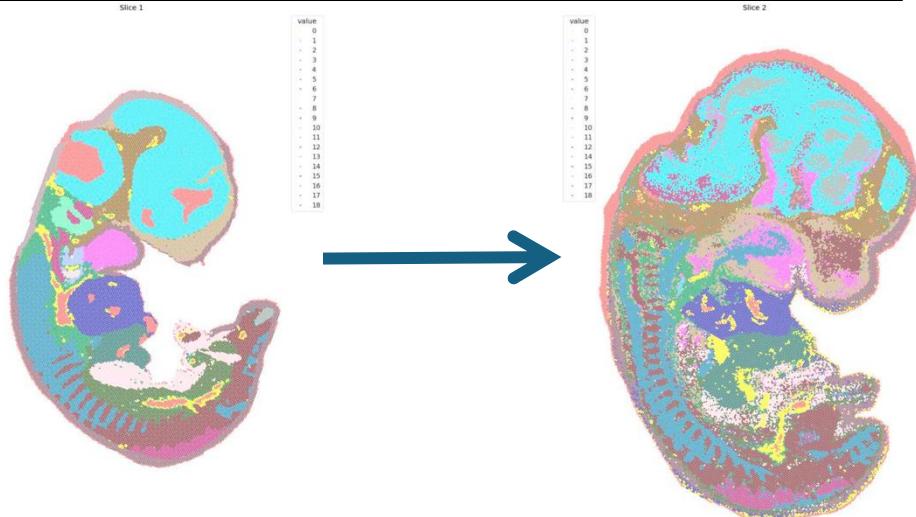
Hidden-Markov OT (Flexibility)



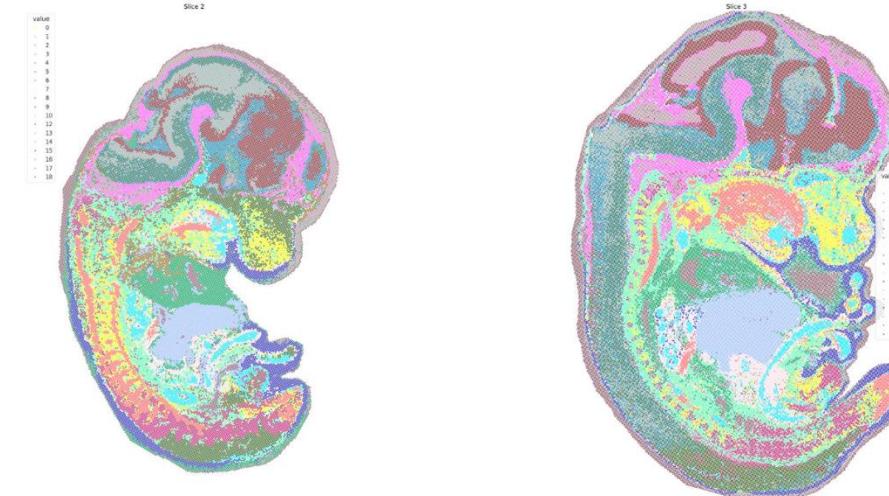
- Highly flexible in terms of input information! One can either run fully unsupervised or constrain any subset of the variables:
 - Cell-type proportions (g_t)
 - Cell to cell-type assignments (Q_t)
 - Cell-type to cell-type (e.g. lineage) transition structure ($T^{(t,t+1)}$)

HM-OT: Flexible Toolbox for (Co) Clustering

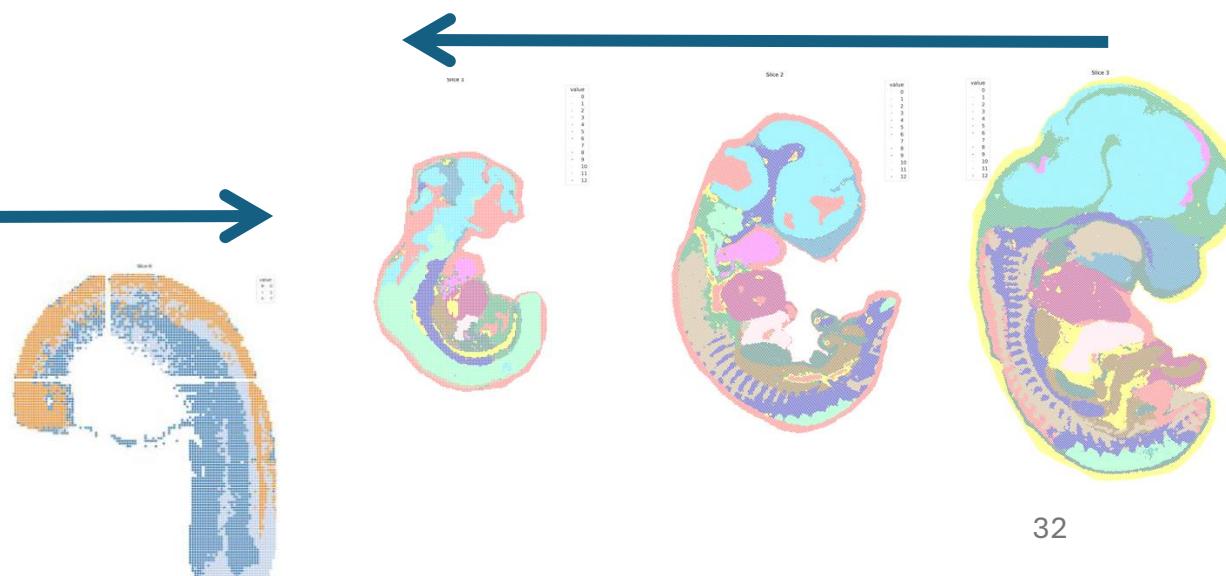
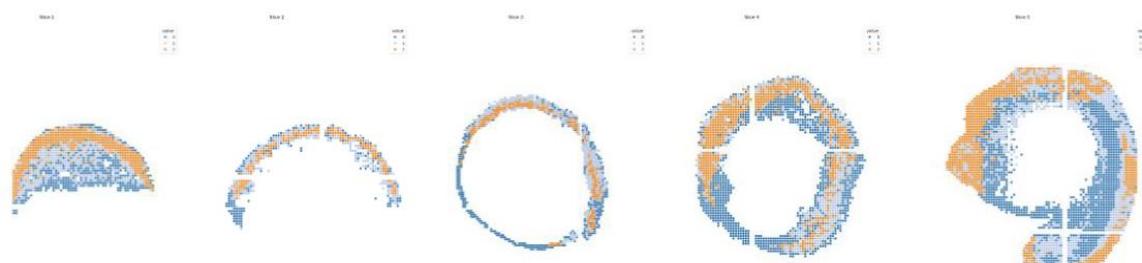
Transfer known clusters forwards or backwards in time to other data



Learn cell state/type from scratch to minimize HM-OT objective



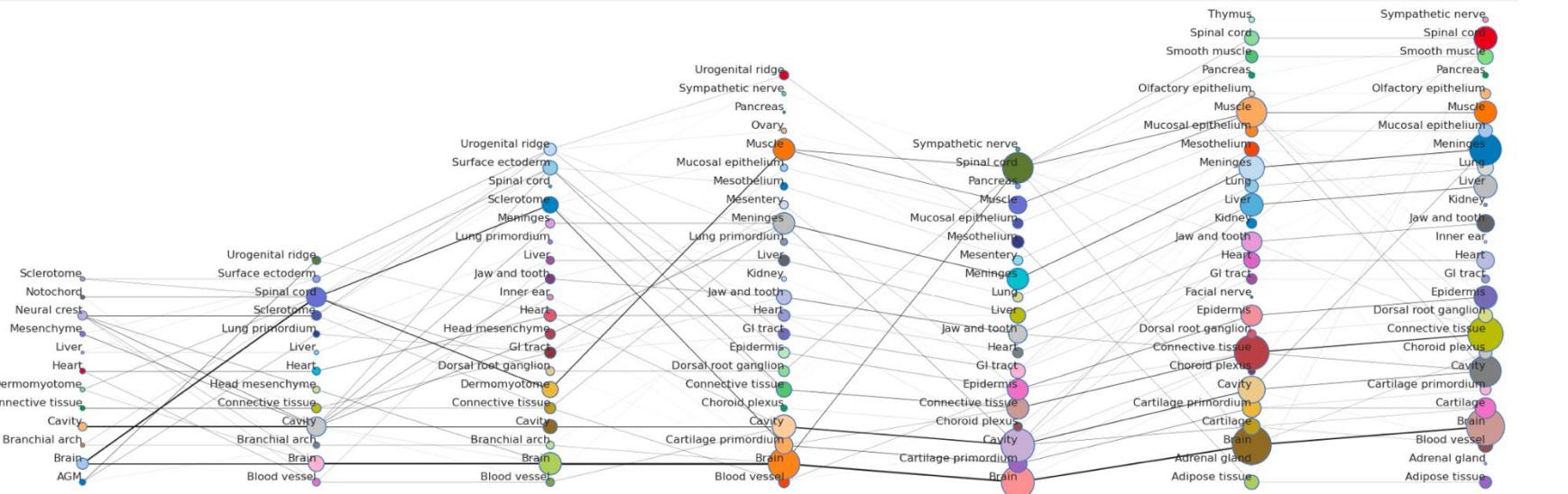
Project or co-cluster cell-types forward and backward in time through differentiation map



Large-Scale Inference of Differentiation Maps

Lightning fast and space-efficient; can scale maps to millions of points!

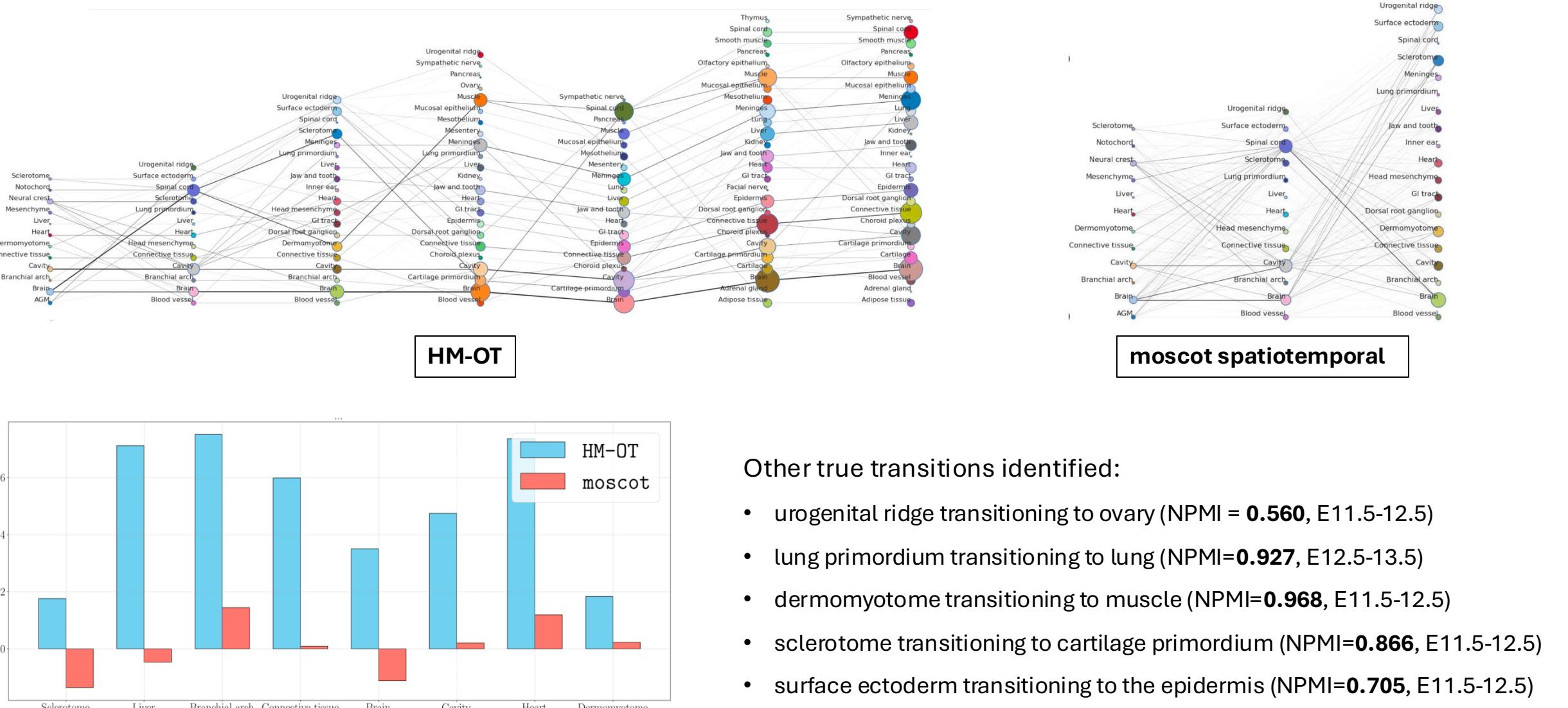
Spatial (Stereo-Seq) Mouse Development (Chen et al '22)



Temporal (Single-Cell) Mouse Embryogenesis (Qiu et al '24)



Large-Scale Inference of Differentiation Maps



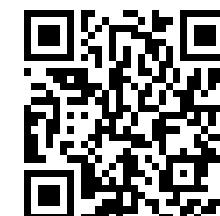
Summary

HM-OT: a scalable algorithm to infer differentiation maps, discover temporal co-clusters, and track cell-types through time and space.

- HM-OT introduces a novel multi-marginal optimal transport formulation to map cell-type differentiation
- Optimizes this factorization across a full time-series of temporal transcriptomics (or other!) data

<https://github.com/raphael-group/HM-OT/>

Thank you!



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